

Error Analysis of the Altimetric Bathymetry Model

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Abstract. The altimetric bathymetry model combines depths derived from satellite gravity data with in-situ data such as soundings and shorelines. We used JAMSTEC multibeam surveys as "ground truth" to test versions of these models. This has revealed two kinds of problems. One is a biased scaling from gravity in milligals to topography in meters in the altimetry prediction band (15-160 km wavelengths). The other is that regionally averaged (> 160 km wavelength) depths seemed to accumulate error over successive versions of the model. These problems were not in version 8.2 but crept in subsequently, and have been mostly mitigated in version 12.1.

The prediction-band errors are particularly evident over a patch of smooth seafloor that lay in a large area unconstrained by ship observations (Box A). Bathymetry versions 9.2, 9.1, 10.1, and 11.1 show errors in depth approaching 150 m, that increase with distance from constraint, and that also increase with successive versions. The depth errors were less than 100 m in bathymetry version 8.2. After correcting the scaling problem, errors in version 12.1 are comparably small. Results are similar over a rough area of seafloor (Box B).

The long-wavelength errors are evident in a focus area in the north Pacific Ocean (Panel C), where the errors bleed even through grid cells having ship constraints. Initializing the 12.1 model to start from S2004 has mostly corrected this problem.

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	-6000		-3000 Depth. m			Ó	ľ

We thank JAMSTEC (Japan Agency for Marine Earth Science and Technology) for making their multibeam data freely available (http://www.jamstec.go.jp/cruiseda

Study Areas A & B		
 Bathymetry model V11.1 		
 Black dots are grid cells containing ship constraints 		
 Differences between JAMSTEC multibeam depths and predicted bathymetry depths are plotted along multibeam track lines 	Contraction of the local division of the loc	
 Box A- Smooth seafloor 		`
 Box B- Rough seafloor 		

Bathymetry Grid Attributes								
Version	Spacing	Node	Projection	Coverage	Released	Based on	Notes	
V8.2	2' longitude	pixel	Mercator	global ± 72°	Nov. 2000	9.1 gravity		
S2004	1' longitude	grid	geographic	global	April 2004	9.1 gravity	V8.2 below 1000 m and equatorward of 72°, GEBCO in shallow water and polar regions	
V9.2	2' longitude	pixel	Mercator	global ± 80.738°	April 2007	16.1 gravity		
V9.1	1' longitude	pixel	Mercator	global ± 80.738°	Aug. 2007	16.1 gravity	changed to 1 grid, new data added, NOAA, NGA, NAVO, SIO effort	
V10.1	1' longitude	pixel	Mercator	global ± 80.738°	May 2008	18.1 gravity	bad track editing and refined grid	
V11.1	1' longitude	pixel	Mercator	global ± 80.738°	Sept. 2008	18.1 gravity	editing and NOAA data added	
V12.1	1' longitude	pixel	Mercator	global ± 80.738°	Aug. 2009	18.1 gravity	scaling correction and initialization from S2004	

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Our analysis of bathymetry version 12.1 (Panel D) reveals that errors are not a function of depth. We find that 50% of the depth errors are less than 50 m (or 1% of depth), and that 90% are less than 220 m (or less than 5.5% of depth).







Panel D

V12.1



V12.1 bathymetry including JAMSTEC MB, m

-6000

-8000

-10000

-4000

-2000

with depth

• Errors show no systematic correlation