

Quality control for Multibeam echosounders at the French Naval Hydrographic Service (SHOM)

Christophe Vrignaud, Sophie Loyer, Patrick Michaux Thierry Schmitt

European bathymetric database and digital elevation model (EMODNET- HYDROGRAPHY initiative)

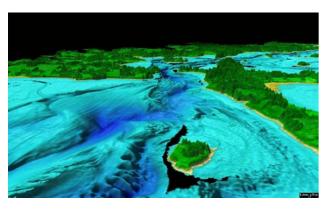
Thierry Schmitt as a servitor of the EMODNET HYDROGRAPHY PROJECT



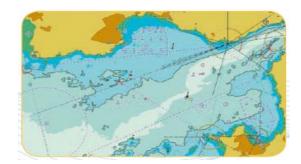




















The Hydrography requirements

- II SHOM's quality control management
- III Conclusion

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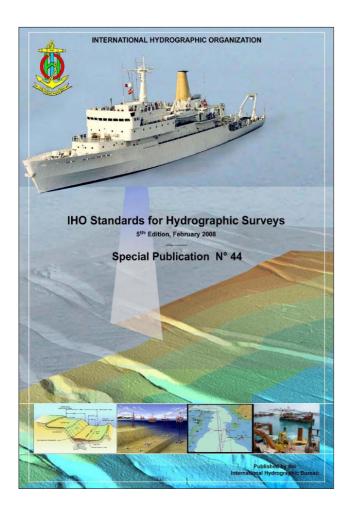
- What is the real need ? - What are the requirements ? Zar Beautemps-Beaupré 1838 - In the end, what is the level of confidence given to data ? ۲ (B) Du bro







IHO Special Publication N° 44, 5th Edition, February 2008



The international conventions give the global frame for the States.

Concerning the requirements, the International Hydrographic Organization gives the **minimum** standards that must be achieved !

- SP44 provides requirements for horizontal and vertical accuracy, for detection features, for exploring methods ...
- SP44 provides also guidelines for quality control.

		· · · · · ·	· .	<u> </u>	
Reference	Order	Special	la	16	2
Chapter 1	Description of areas.	Areas where under-keel	Areas shallower than 100	Areas shallower than 100	Areas generally deeper than
		clearance is critical	metres where under-keel	metres where under-keel	100 metres where a general
			clearance is less critical but	clearance is not considered to	description of the sea floor is
			features of concern to surface	be an issue for the type of	considered adequate.
			shipping may exist.	surface shipping expected to	
		-		transit the area.	
Chapter 2	Maximum allowable THU	2 metres	5 metres + 5% of depth	5 metres + 5% of depth	20 metres + 10% of depth
	95% Confidence level				
Para 3.2	Maximum allowable TVU	a = 0.25 metre	a = 0.5 metre	a = 0.5 metre	a = 1.0 metre
and <u>note 1</u>	95% Confidence level	b = 0.0075	b = 0.013	b = 0.013	b = 0.023
Glossary	Full Sea floor Search	Required	Required	Not required	Not required
and <u>note 2</u>					
Para 2.1	Feature Detection	Cubic <i>features</i> > 1 metre	Cubic <i>features</i> > 2 metres, in		
Para 3.4			depths up to 40 metres; 10%	Not Applicable	Not Applicable
Para 3.5			of depth beyond 40 metres	Not Applicable	Not Applicable
and <u>note 3</u>					
Para 3.6	Recommended maximum	Not defined as <i>full sea floor</i>	Not defined as <i>full sea floor</i>	3 x average depth or 25	4 x average depth
and note 4	Line Spacing	search is required	search is required	metres, whichever is greater	
				For bathymetric lidar a spot	
				spacing of 5 x 5 metres	
Chapter 2	Positioning of fixed aids to				
	navigation and topography	-	-	-	_
and <u>note 5</u>	significant to navigation.	2 metres	2 metres	2 metres	5 metres
	(95% Confidence level)				
	(serv conjuncte terety				
Chapter 2	Positioning of the Coastline				
and note 5	and topography less	10 (20 metres	20	20
ana <u>note 5</u>	significant to navigation	10 metres	20 metres	20 metres	20 metres
	(95% Confidence level)				
C 1 · · · · · ·	34 14 48 4				
Chapter 2	Mean position of floating		10 metres		
and <u>note 5</u>	aids to navigation (95%	10 metres	10 metres	10 metres	20 metres
	Confidence level)				

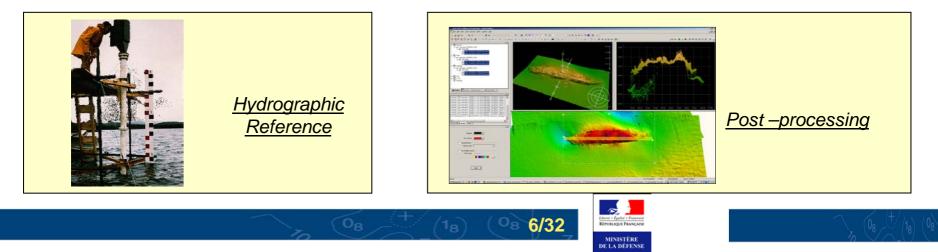




Multibeam: sensor for modern hydrography

From the pings to the post-processed data: not a simple task !





П	The Hydrography requirements		
Ш	SHOM's quality of	control management	
Ш	Conclusion		
		- Training of surveyors	
		- Patch tests and calibration	
		- Reference areas	
		- Databases	





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		- Training of surveyors - Patch tests and calibration	





Training



S44 standard states (extract from the 5th edition – February 2008):

All components **and their combination** must be capable of providing data to the required standard. The hydrographic office / organisation needs to satisfy itself that this is so by, for example, conducting appropriate trials with the equipment to be used and by ensuring that adequate calibrations are performed prior to, as well as during and, if appropriate, after the survey being carried out. The surveyor is an essential component of the survey process and must possess sufficient knowledge and experience to be able to operate the system to the required standard. Measuring this can be difficult although surveying qualifications (e.g. having passed an IHO Cat A/B recognised hydrographic surveying course) may be of considerable benefit in making this assessment.

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SHOM trains its staff in its own training centre: « SHOM's school »

- Hydrographic training programme for surveyors: FIG/IHO/ACI S-5 cat. B accredited (submitted for reconduction in 2011).
- Survey engineers are trained in ENSTA-Bretagne (S-5 cat. A programme)

• Vocational training throughout the career: hydrography, oceanography, nautical cartography, geophysics, quality management.

• Training effort (2010):

Global : 120 initial trainings and 214 vocational trainings in hydrography, oceanography, nautical cartography, geophysics, quality management.







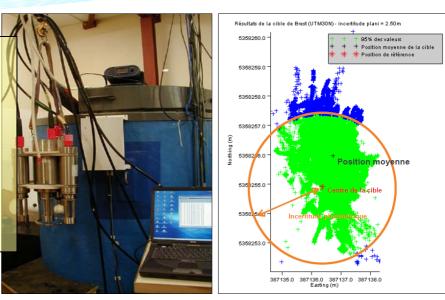
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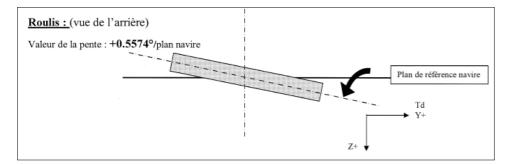




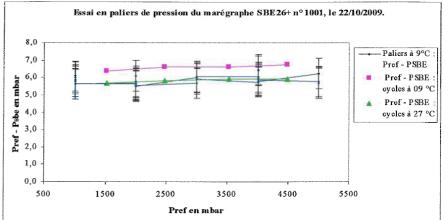
Sensors calibration (for MBES)

- Sound velocity sensor: every year
- Tide gauge: every year
- Positioning service (GPS target): as often as possible
- Lever arms and angular offsets: every 2-3 years in dry dock)





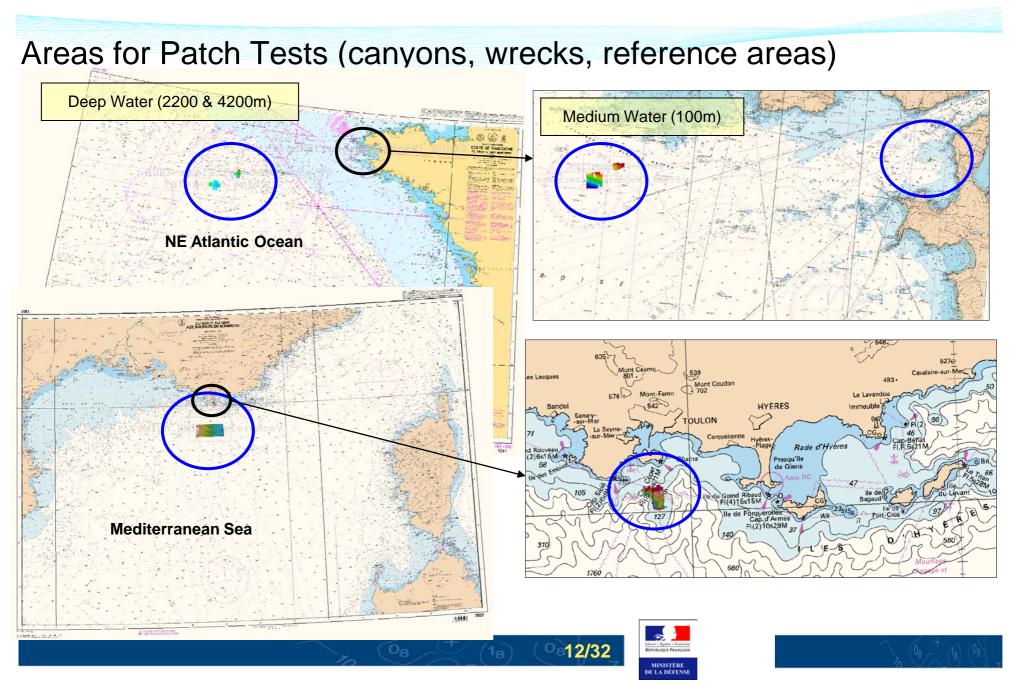
Uncertainties of the sensors are provided via the TPU to processing algorithms (CUBE)





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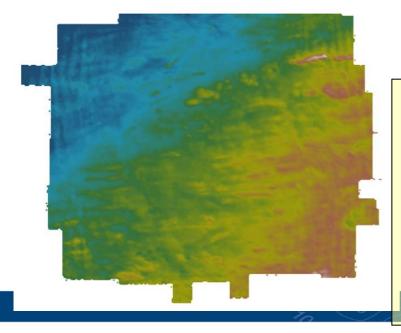


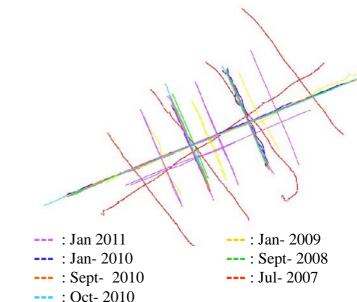
Comparison of multibeam lines to a reference surface: A vertical checking !

Main characteristics of a reference area:

- Small and flat area (which minimizes the effects of positioning errors)

-Exempted of known tide or hydrological complexity



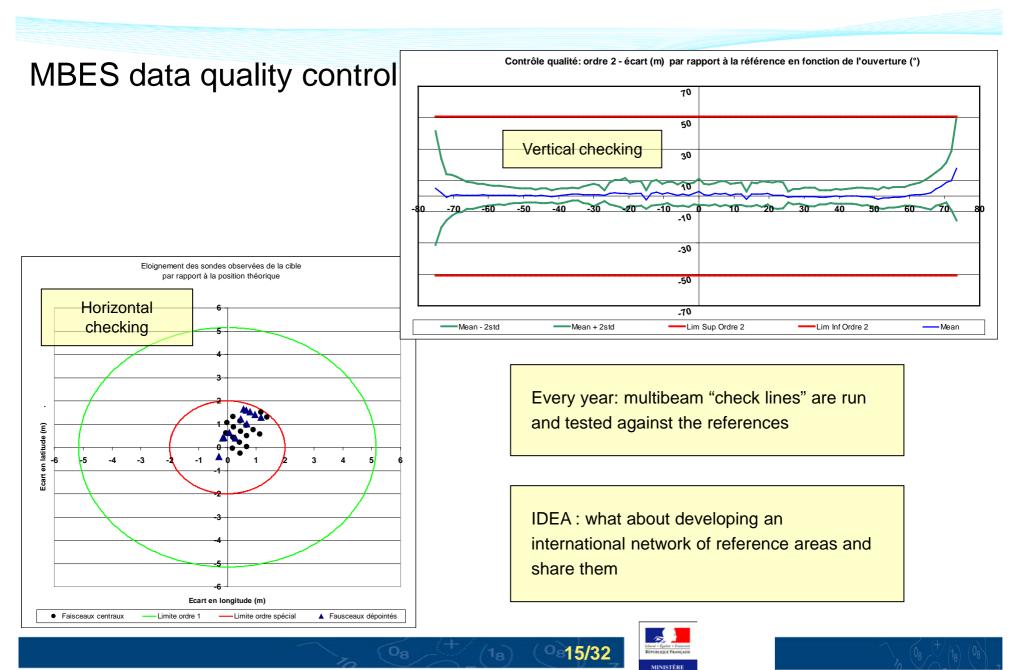


Individual analysis of each data set:

-Chasing for systematic errors which can invalidate the survey,

-CUBE surfacing of the whole soundings data set, editing and examination of hypothesis to verify CUBE decisions,

=> Evaluating the performance of "the new survey" with respect to the other composing the reference surface.



DE LA DÉFENSI

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Three Databases

1 - Equipment database

Repairings registration during all the life of the devices

A ES	Résultat	s de la r	echerch	e d'instruments
Recherche Instruments	Critères : REP	SHOM = "20	0140" N° S	érie = "" Désignation = "%"
<u>Notices et</u> logiciels	Recher	and the second second		<u>Exporter</u>
constructeurs	Code santé			
Modèles		<u>20140</u>	<u>1516</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
Fiche interv.		<u>20140</u>	<u>1539</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
Actions		<u>20140</u>	<u>1554</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
<u>Mise à jour</u> Administration		<u>20140</u>	<u>1557</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
Aide		<u>20140</u>	<u>1562</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
<u>Manuel utilisat.</u> Nous contacter		<u>20140</u>	<u>1572</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
3 1 2 2		<u>20140</u>	<u>1630</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
Version		<u>20140</u>	<u>1659</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
V 1.0a		<u>20140</u>	<u>1666</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
1 Bai		<u>20140</u>	<u>1678</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE
A	•	<u>20140</u>	<u>1685</u>	SONDEUR MULTIF. EM3002:ELECTRONIQUE

2 - Documentation database Guides, manuals (updated after each evolution of a system)

Non protégé		
DO/MIP		
Guide		
Evaluation des performances bathymétrique des sondeurs multifaisceaux	s	
http://agora.shom.fr/docQual/2005/GU/GU2005-043		2
Etat : Approuvé (à contrôler)		
Version : 1.3.2 Dernière modification le 2009/03/05 09:12		

Editeur patrick.michaux@shom.fr Chef.de.projet.SMF je 2006/01/25 17:33

martial.jaouen@shom.t Adjoint processus le 2006/02/14 09:56 Approbateur michel.even@shom.fr Chef CH le 2006/02/17 16:02

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Libert - Egalu - Francesin République Française MINISTÈRE DE LA DÉFENSE <u>3 - Configuration database</u> Software, firmware and hardware configuration Settings configuration (sea test after upgrades)

2.2. Transducteur.	
Numéro de série	213
Rattachement en X p/r au point de référence	22.78
Rattachement en Y p/r au point de référence	0.01
Rattachement en Z p/r au point de référence	6.67
Angle d'installation en roulis	0.13
Angle d'installation en tangage	1.95
Angle d'installation en cap	0.12
Biais en roulis avec M-PHINS	-0.13
Biais en tangage avec M-PHINS	-0.23
Biais en cap avec M-PHINS	0.20
Outerbeam angle offset	0.00
Biais en roulis avec SEAPATH	-0.24
Biais en tangage avec SEAPATH	-0.22
Biais en cap avec SEAPATH	0.00

2.3. Système temps réel.

Version SIS	Version 3.6.1
HWS12	N°632

2.4. Firmware.

Version BSP Master	BSP version 1.5.5 du 050810
Version CPU	CPU (Old) version 1.3.3 du 060904
Version SPRX	SPRX version 1.0.6 du 991014
Version DDS	DDS version 3.27 du 050810



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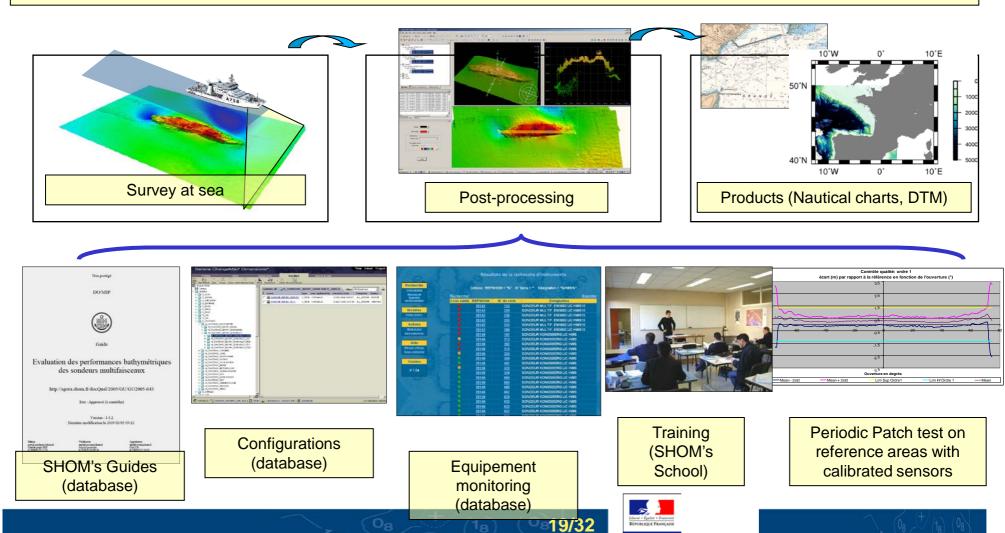




Take home message :

 frequent controls, associated with clear procedures and training of the surveyor guarantees a level of quality of bathymetric data and the lifelong performances of Multibeam echosounder systems

- Sharing reference areas would help comparing data quality amongst bathymetric data holders



MINISTÈRE JE LA DÉFENS

European bathymetric database and digital elevation model (EMODNET- HYDROGRAPHY initiative)

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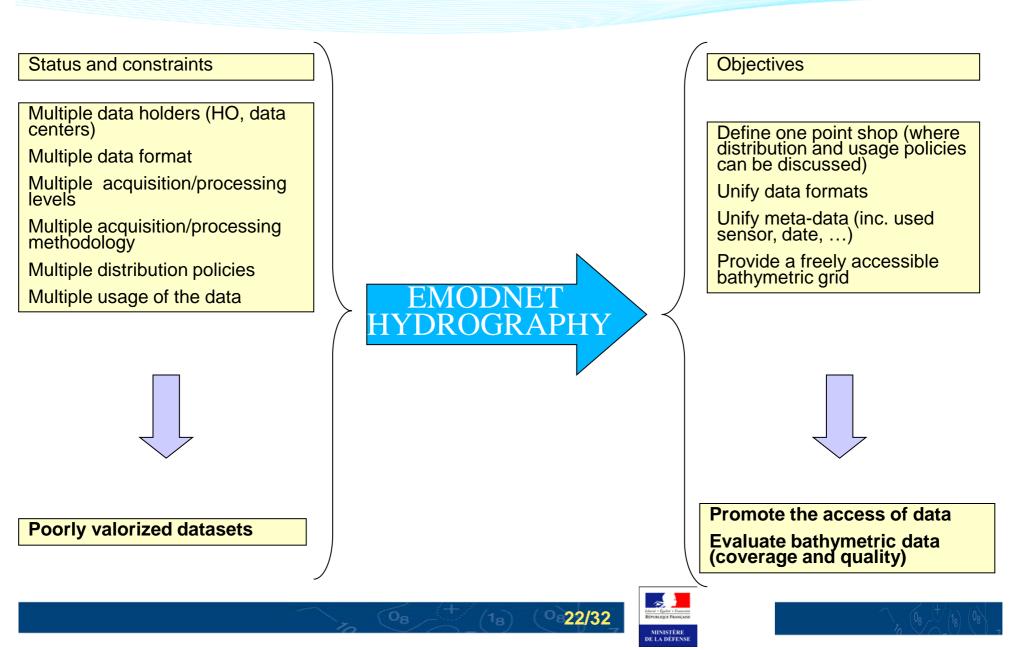
Context in terms of bathymetry in Europe Pilot EMODNET project

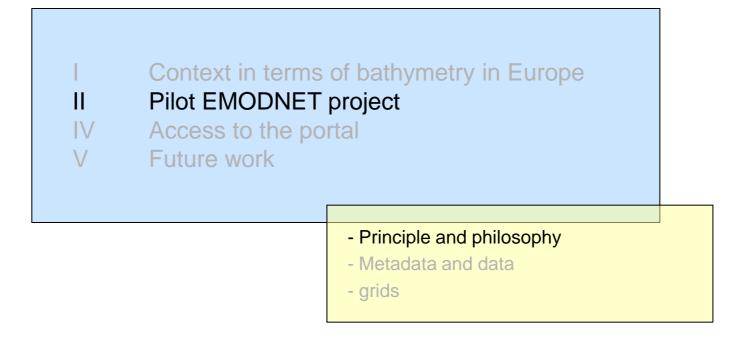
- IV Access to the portal
- V Future work















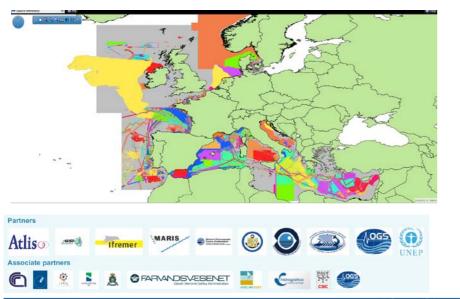
Pilot project

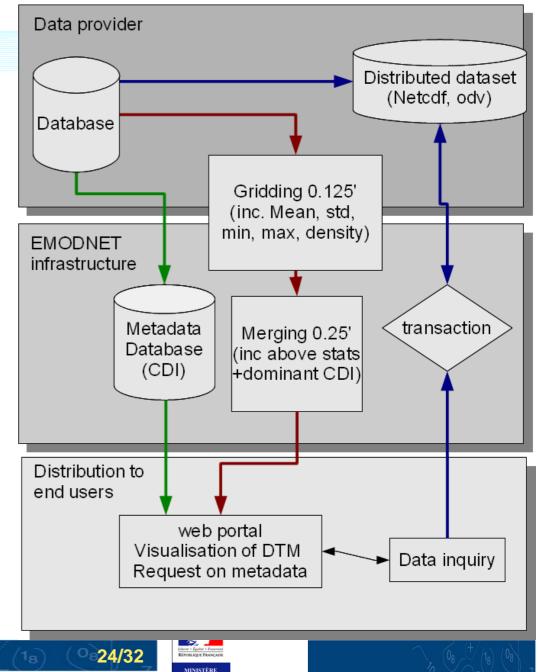
Distributed infrastructure

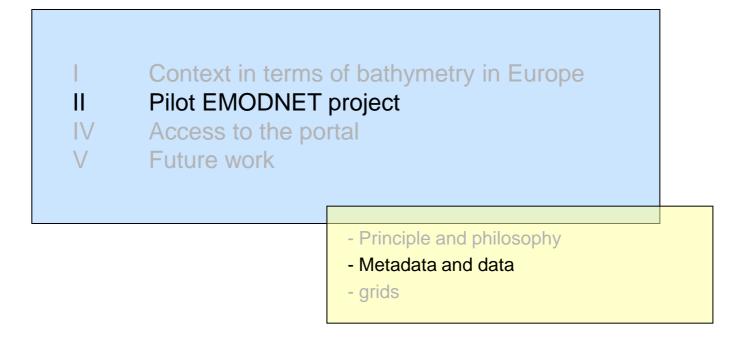
Encompass interests/constraints of HOs, data centres, industry

Facilitate the distribution of the data on the provider side

Maximise the use of the data











Common Data Index (CDI)

Data providers generate an xml file per data set

Formatted metadata are displayed on a web portal and are free to use

Data are staying by the data provider

Ideally data are formatted in ODV or NetCDF-CF (undergoing work)

Data are distributed to the end-user after a phase of mutual agreement (condition of usage, principle of distribution)



ELABORACIÓN DE MARAS DE HABITATS Y CARACTERIZACIÓN DE LOS FONDOS MARINOS DE LA PLATAFORMA CONT

Marine gaology

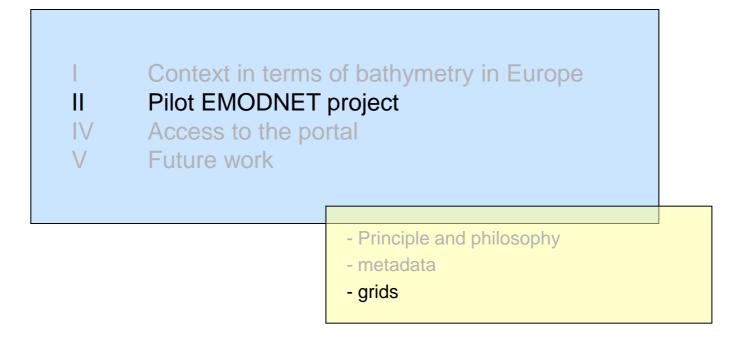
Climate and Forecast NetCDF Version 3.5

Variables measu Abstract

Data set cr

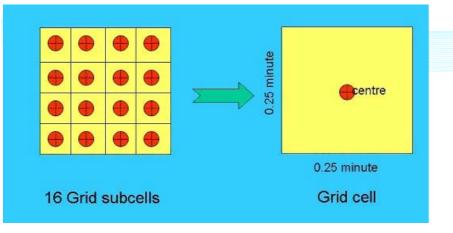
Soanish Oceanographic Institute

COI-partner







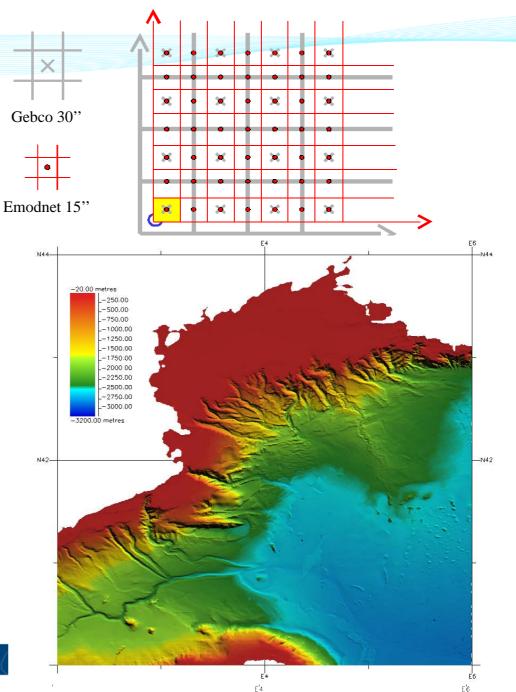


Minimum cell depth Maximum cell depth Average cell depth Standard deviation Number of depths used for computation of cell depth Number of sub-cells used for the computation of the average cell depth

Major contributor of the cell

Spline surface (with holes filled with GEBCO 30")





I Context in terms of bathymetry in Europe II Pilot EMODNET project IV Access to the portal V Future work

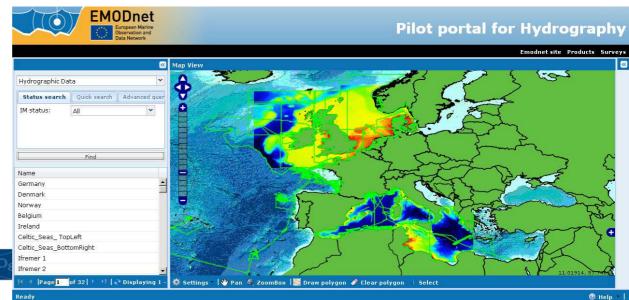






	ODne European Mar Observation an Data Network	ne		al for Hydrograp	
((Cart: 0 Dataset(s) Proc teset all steps	eed to check	out Reset basket	Export Store query	Summary Hide map	?
Tools () () () () () () () () () ()	Adto		^{50 ° 100 Records}	Layer control CDI entry Points 2 CDI entry Points 2 CDI entry Tracks 2 CDI entry Tracks 2 Grid Lines 2 Regional sea 2 Regional sea 2 Main sea 3 Main sea 3	s list
Ø	— *	Data set name 🕏	Variables measured	Instrument / gear type	Show
Time period	Γ	540-8201001900-2	Marine geology > Gravity, magnetics and bathymetry Terrestrial > Terrestrial	multi-beam echosounders	3
deasuring area type	Γ	540-8201001900-1	Marine geology > Gravity, magnetics and bathymetry Terrestrial	multi-beam echosounders	3

http://www.emodnethydrography.eu/



I Context in terms of bathymetry in Europe II Pilot EMODNET project IV Access to the portal V Future work







GENERAL

Evaluate the European bathymetric coverage and set the effort to undertake to get an up-todate coverage

Extend to other area (Black Sea, Baltic Sea, North-East Atlantic)

Attract new data providers (inc. Industrial sector and crowd-sourcing)

GRID

Evaluate the quality of the grid

Improve the quality of the grid (i.e. filtering out dataset, smoothing/interpolation algorithm)

Include source data used for the creation of the GEBCO grid (i.e. only originating from NGDC database)

Converge with new standards (IHO S10x) and europeans obligations (INSPIRE) for data and metadata distribution



