

OCEAN DISCOVERY XPRIZE

GEBCO-Nippon Foundation Alumni Team's solution for Shell Ocean Discovery XPRIZE Competition

presented on behalf of the GNFA Team by Yulia Zarayskaya Geological Institute of Russian Academy of Science





GEBCO Symposium: Map the Gaps Portsmouth, 2019



A \$7 million global competition challenging teams to advance deep-sea technologies for autonomous, fast and high-resolution ocean exploration.

Shell

OCEAN DISCOVERY

Create solutions that advance the autonomy, scale, speed, depths and resolution of ocean exploration http://oceandiscovery.xprize.org

Preliminary phase (Dec 2016): written description of the proposed solution

Round 1 (Nov 2017) Min. 100 km² in 16 hours 48 h of data processing Max. Depth – 2,000 m Round 2 (Nov 2018) Min. 250 km² in 24 hours 48 h of data processing Max. Depth – 4,000 m

PRIZE



SHIPOWNERS

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OmniAccess





7F

日本 武回



RZE



Shell OCEAN DISCOVERY



New **autonomous surface vessel** capable of AUV deployment & retrieval

- Hushcraft Limited SEA-KIT USV Maxlimer
 with KM HiPAP
- Remote and Autonomous operations facilitated by Kongsberg Maritime K-MATE

Kongsberg Maritime HUGIN AUV

- Round 1: Ocean Floor Geophysics *Chercheur* AUV: 3,000 m
- Round 2: Kongsberg Maritime: 4,500 m

Seafloor bathymetry and imagery

- Fusion of EM2040 & EM304 MBES, HISAS real aperture bathymetry, HISAS synthetic aperture bathymetry and side-scan imagery
- Spot-focused synthetic aperture HISAS imagery and bathymetry

ROUND 2 PRODUCTS

SURFACES

- 5 m resolution grid of overall combined bathymetric dataset
- 2 m resolution grid of HISAS1032 wide-area mode data
- 1 m resolution grid of standard HISAS1032 mode data
- 1 m resolution grid of EM2040 data
- 5 m resolution grid of EM304 data

2 7 3

IMAGERY

- 10 cm resolution mosaic of standard HISAS1032 mode
- 1 m resolution mosaic of HISAS1032 wide-area mode
- 1 m resolution mosaic of EM2040 backscatter
- 2 cm resolution Spot processed side-scan images of objects (produced using KM Reflection software)
- 3D images: bathymetry drapes (produced using Fledermaus), point cloud images (using Qimera) produced remotely at UNH



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PRIZE

ROUND 2 WORK HUBS

- 1. Survey equipment
- 2. Operations Center
- 3. Data Processing ('Mission Control')

+ NETWORK





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Automated work flow – data to information



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440 -50 m

100 m

Object - Size: 0.33 x 0.49 m; Height: 0.14 m

