E/V Nautilus Mapping for Ocean Exploration





Dr. Nicole Raineault Vice President of Exploration & Science Operations Ocean Exploration Trust

> November 15, 2017 Map the Gaps

Nautilus Exploration Program













• Kongsberg EM302 multibeam echosounder (bathymetry, backscatter, water column)

 Knudsen 3.5/15 kHz systems (Chirp sub-bottom, single beam)

• High resolution ROV-based M3 sonar, laser light mapping, and stereo-pair camera



System Capabilities:

- Mapping speed: 8-10 knots
- Coverage: 2.5-5.5x water depth
- Depth: 30-7000 m (60-70°)
- Resolution: ~1% water depth
- Operational modes:
 - Bathymetric mapping
 - Water column (seep) mapping

Mapping Products Per Survey:

- GSFs, geotiff images & floating point, SD file, KML, polygon, survey report, line file report, processing log
- Outreach products (handled by production for NL & social media)



1.7K Views







10 m grid



300 m



30 m





Important Factors for Exploratory Seafloor Mapping

- High quality mapping data
 - Annual MAC inspection
 - Clean transducers
 - Valid sound velocity information
 - UCTD & XBTs
- All possible data types or products with links to data sources/raw data
- Metadata simplification/tools
- Data submission simplification
- Gap analysis & data quality products
- Forum for community survey plans



Internships: students join us at sea Scientists Ashore: join in the discussion & provide AOIs for mapping Ship Charters: Use *Nautilus* for your seafloor mapping project www.oceanexplorationtrust.org Watch at: www.nautiluslive.org



Expedition Planning & Data Availability

- Lead scientist represents wider scientific community interests
- Scientists Ashore
 - Sign up online (www.oceanexplorationtrust.org)
 - Planning calls
 - Receive cruise and dive plans and daily ship updates
- Data, video, and samples available to all after cruise
- Annual reports in a supplement published by the Oceanography Society



http://tos.org/oceanography/issue/volume-30-issue-01-supplement